ABSTRACT OF THE DISCLOSURE

In a steer-by-wire vehicle steering apparatus including a communication navigation system capable of obtaining an absolute vehicle position, a control device controls a steering motor in response to detection by a detection section in such a manner that an actual angle of travel direction of the vehicle and steering angle of a steering operator member agree with each other. Calculation section calculates an angle of travel direction of the vehicle on the basis of the absolute vehicle position obtained via the navigation system, so that the drive section can be controlled more accurately on the basis of the calculated angle.

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